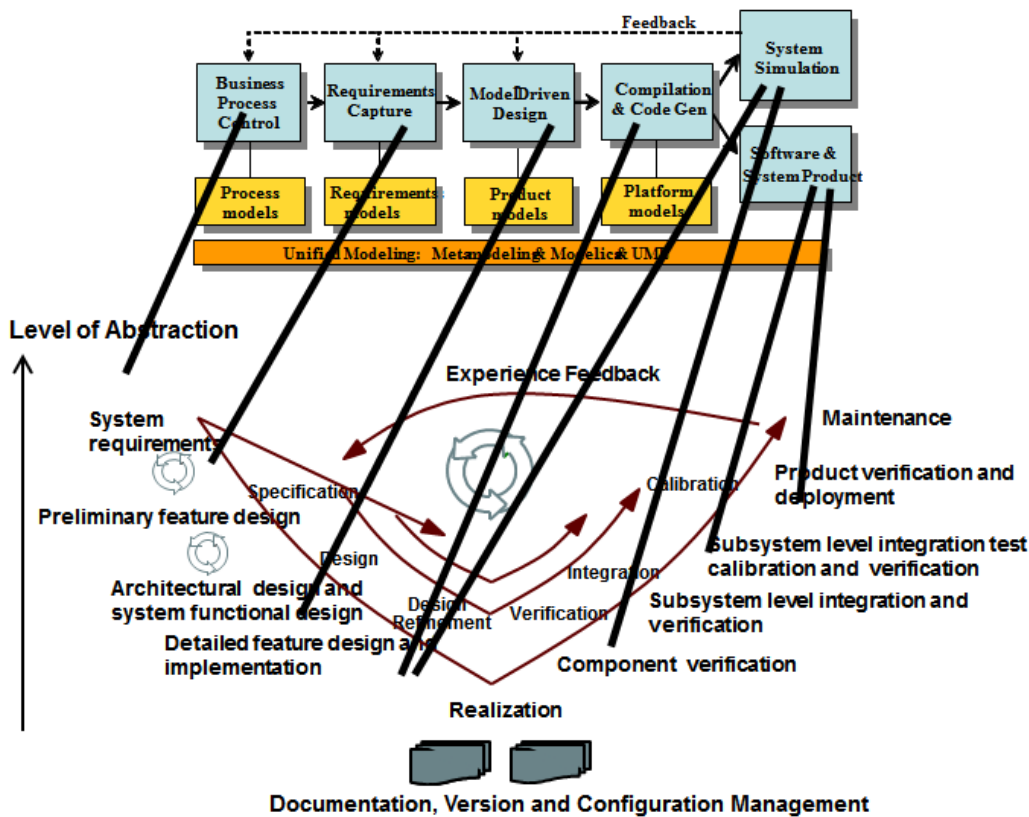


The Need for Comprehensive Whole-life-cycle Systems Engineering Tool Support for Cyber-Physical Systems



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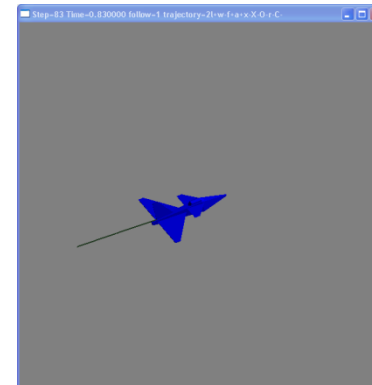
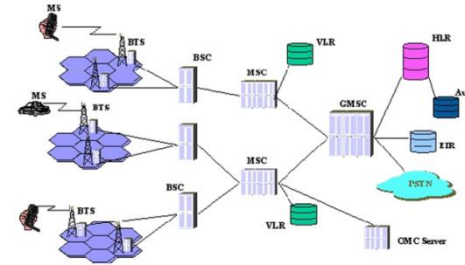
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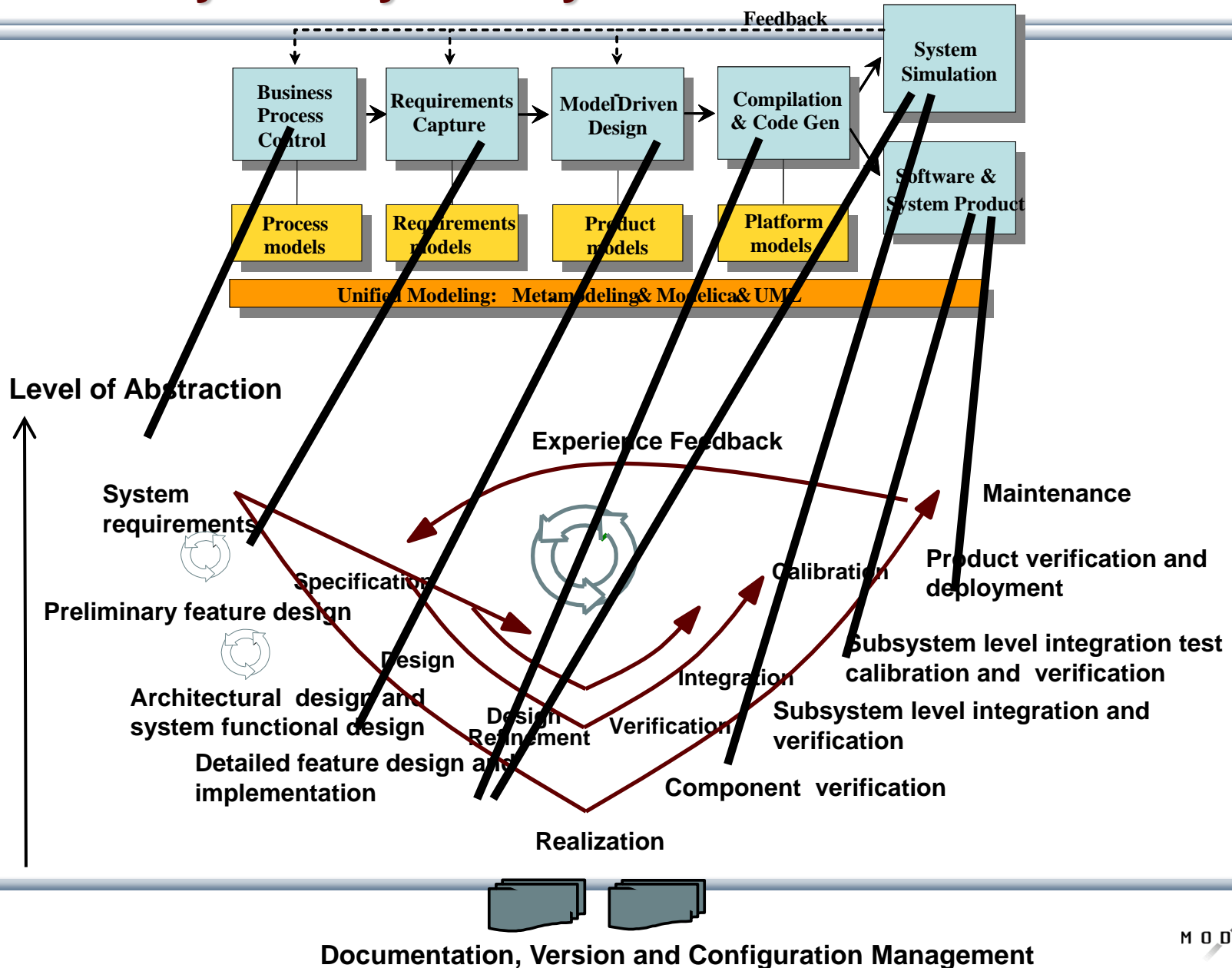


Industrial Challenges for Complex Cyber-Physical System Products of both Software and Hardware

- Increased **Software** Fraction
- **Shorter** Time-to-Market
- Higher demands on effective strategic **decision** making
- **Increased** number of **stakeholders** → increased uncertainties on the system and difficulties in reaching a common agreement
- **Cyber-Physical** (CPS) – Cyber (software) Physical (hardware) products



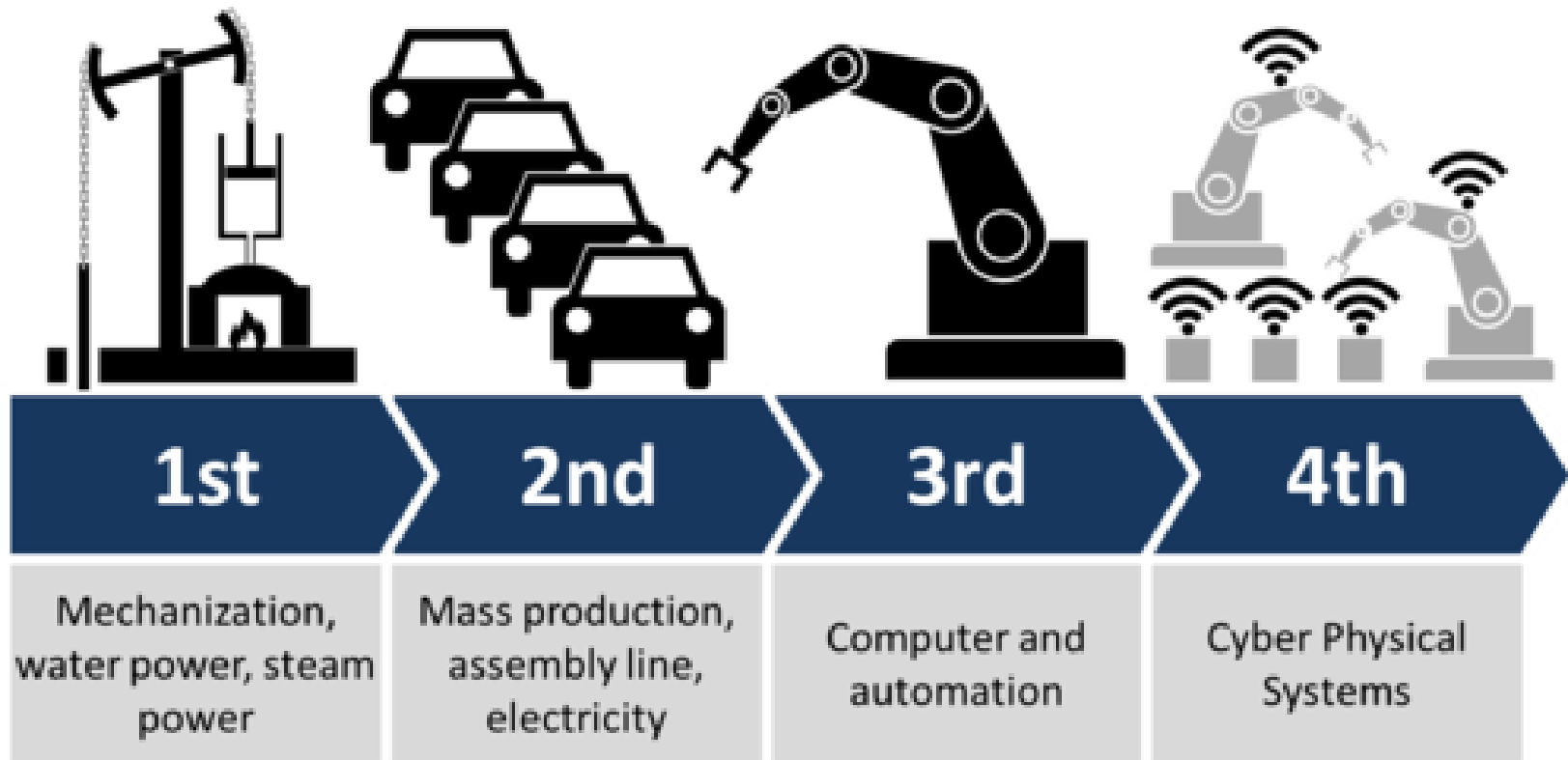
Need for Comprehensive Approach to Systems Engineering of Whole Cyber-Physical Systems Products



Overview of this Talk

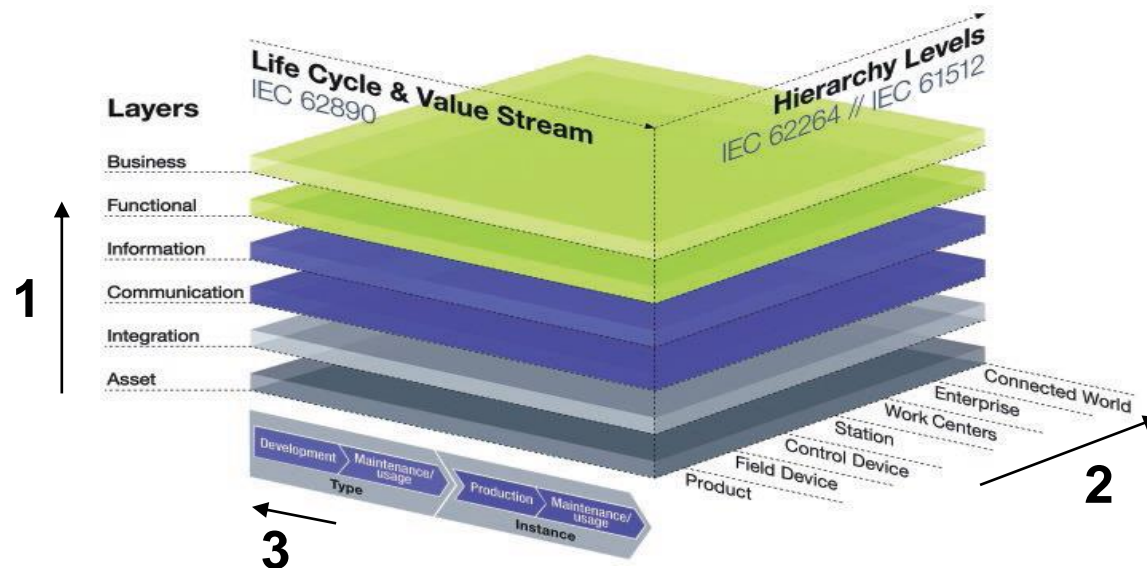
- Need of **whole** product systems engineering
- Taking into account the **assumptions** about the **environment** of the system
- **Industrie 4.0** background
- **Requirement** engineering, debugging and verification
- **Integrating** requirement engineering into CPS systems engineering
- The **whole picture** – what is needed for comprehensive systems engineering

Industrie 4.0 – The Fourth Industrial Revolution (also called digitalization)



Industrie 4.0 Reference Architecture

- Provides a **global picture** of the engineering needs in terms of MBSE. Only a tiny fraction is achieved today.
- **Missing** in particular:
 1. **Bridging physical** (asset) layer (e.g., Modelica) to the **functional** layer (e.g., SysML) (OPENPCS)
 2. **Modelling, debugging, verifying requirements** upstream detailed design (Need for new requirement modeling language?)
 3. Modelling and simulation, large systems with **mode switching** (follow-up of MODRIO)



Industrie 4.0 Design Principles

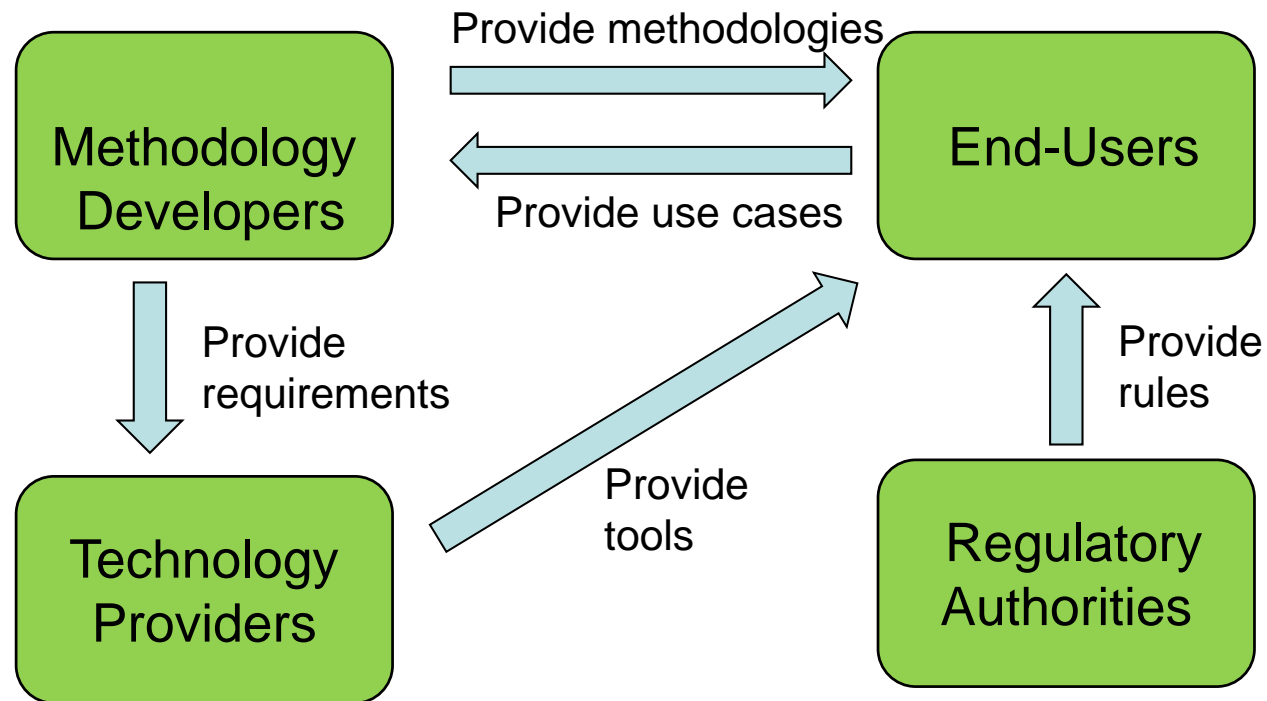
- **Interoperability** – ability of machines, devices, sensors, and people to communicate with each other via the Internet of Things
- Information **transparency** – ability of information systems to create a virtual model of the physical world e.g. by enriching digital plant models with sensor data
- Technical **assistance** – ability of assistance systems to support humans by aggregating and visualizing information comprehensibly for making informed decisions
- **Decentralized** decisions – ability of cyber physical systems to make decisions on their own and to perform their tasks as autonomously as possible.

Some Industrie 4.0 Challenges

- **IT security** issues – aggravated by need to open up previously closed production
- **Reliability** and stability – needed for critical machine-to-machine communication
- **Protect** industrial knowhow – e.g. contained in industrial automation equipment and software
- Lack of adequate skill-sets – needed for the new technology
- Loss of jobs – to automatic and IT-controlled processes

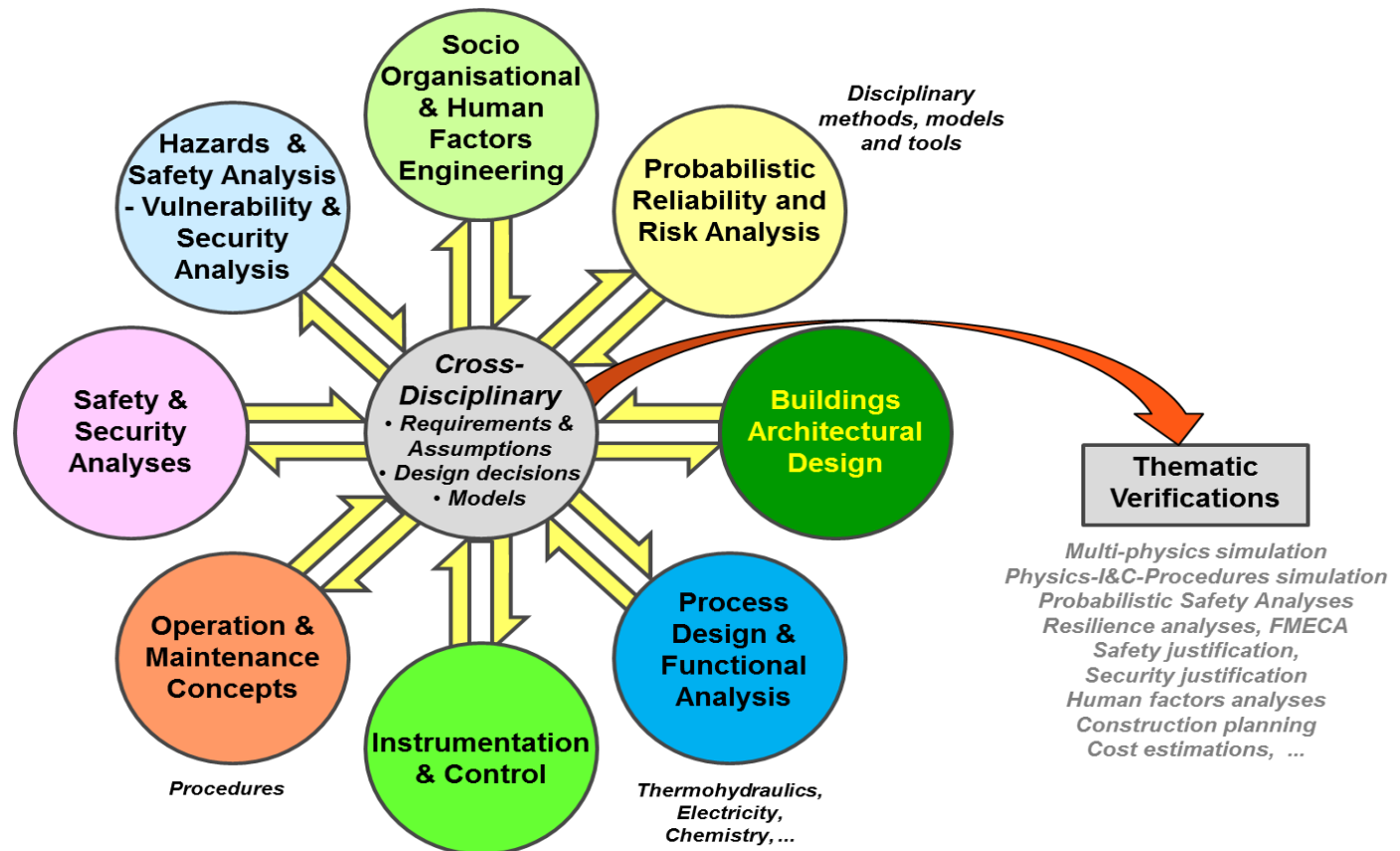
Three Roles in Value Chain of CPS Development

- **End-users** – building and operation of CPS
- **Technology providers** – provide and distribute tools
- **Methodology developers** – develop methods for model-based systems engineering
- **Regulatory authorities** – provide rules to operators for ensuring the stability of large distributed systems



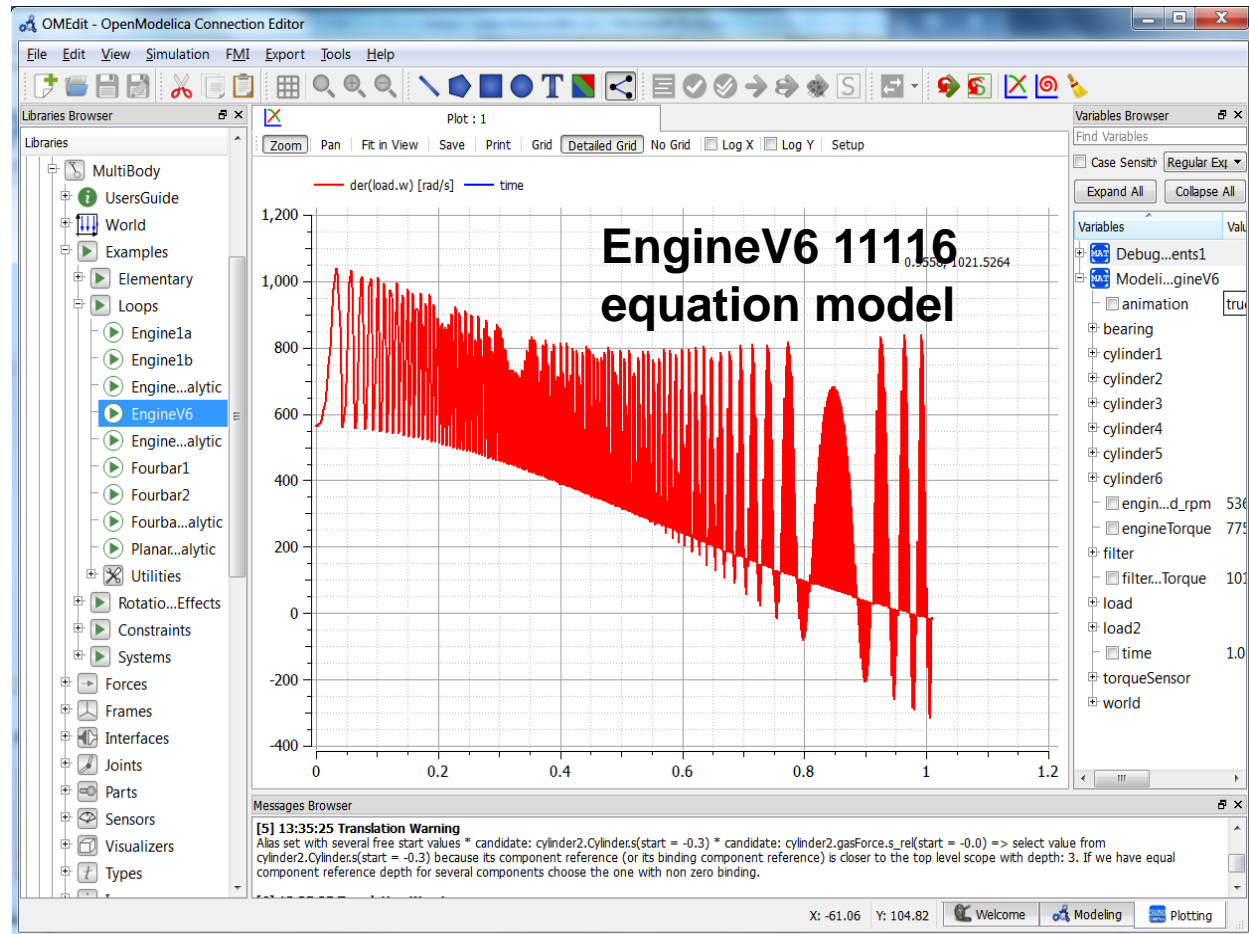
System Co-Design via Requirements Modeling

- Need for a **new neutral language** to **coordinate** all **engineering disciplines** via the **formal** expression of **requirements** and **assumptions** (formal == that may be **analyzed/simulated** at each step of the engineering process)



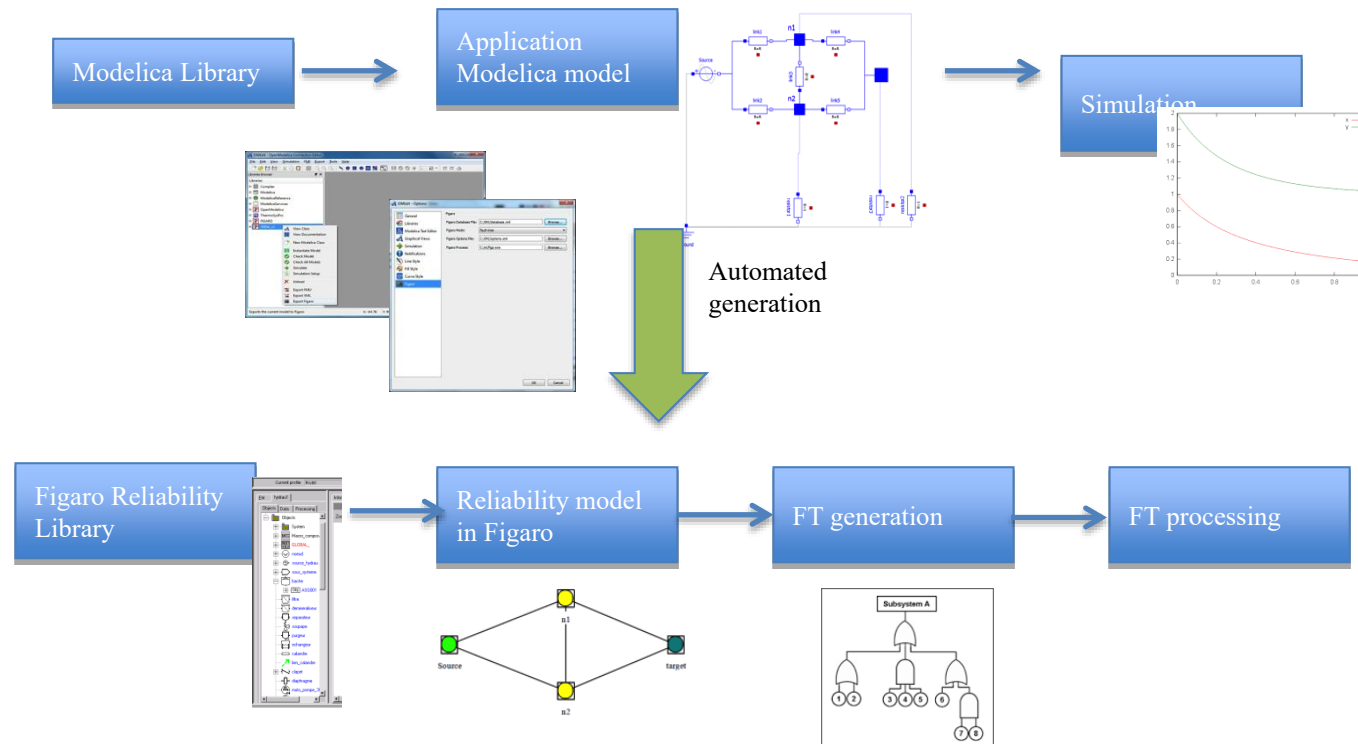
OpenModelica – Free Open Source Tool developed by the Open Source Modelica Consortium (OSMC)

- Graphical editor
- Model compiler and simulator
- Debugger
- Performance analyzer
- Dynamic optimizer
- Symbolic modeling
- Parallelization
- Electronic Notebook for teaching



Model-based Failure Mode and Effects Analysis

- Modelica models augmented with reliability properties can be used to generate reliability models in Figaro, which in turn can be used for static reliability analysis
- Prototype in OpenModelica integrated with Figaro tool

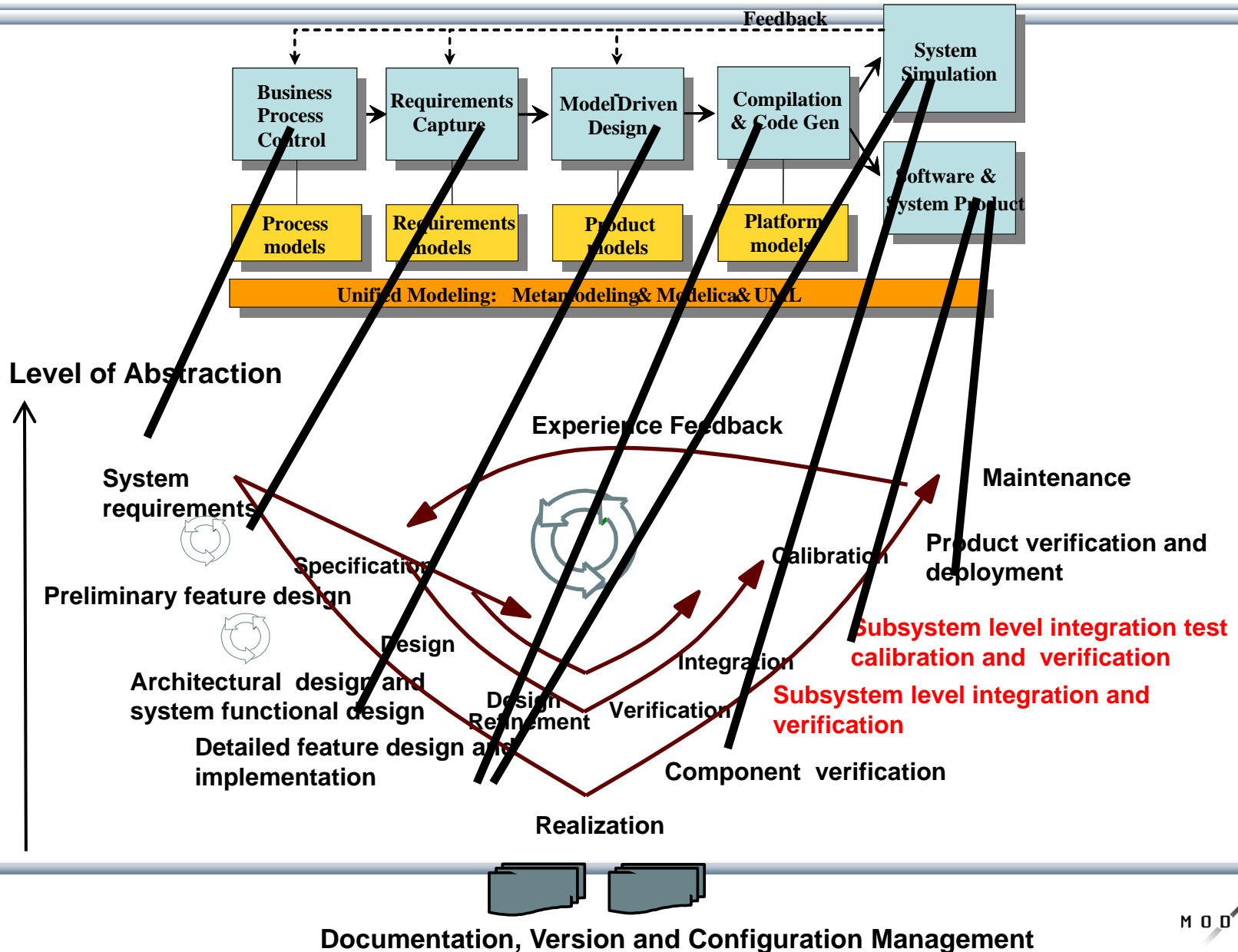


Dynamic Verification/Testing of Requirements vs Usage Scenario Models

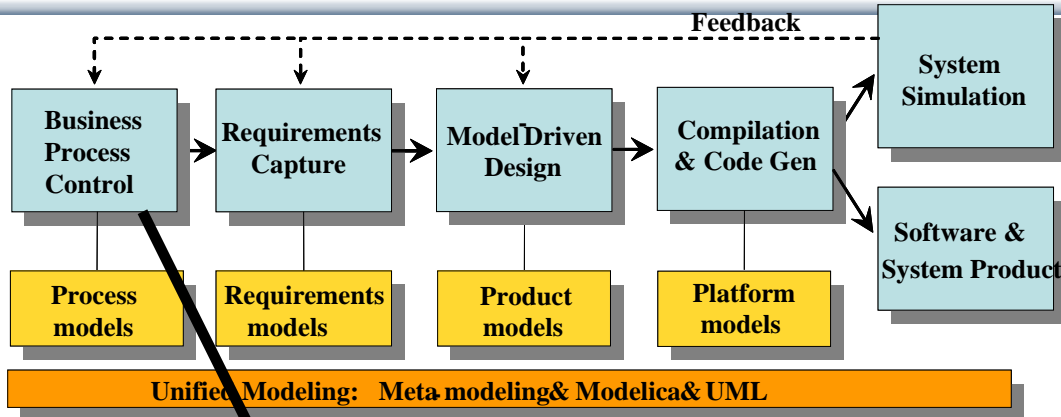
The image displays a collage of software interfaces related to dynamic verification and testing. Key elements include:

- Simulink:** A screenshot of a Simulink model titled "DoubleLaneChangeAndBraking" showing a car on a road with lane markings and control signals.
- Modelica:** A screenshot of a Modelica model titled "Optimizing the Design of an Ice Tank Carriage" showing a mechanical assembly with various components and parameters.
- Van der Pol Model:** A central window titled "Van der Pol Model" containing:
 - Code:** A snippet of Modelica code defining the Van der Pol oscillator model with parameters like λ and μ .
 - Simulation:** A plot showing the simulation results of the Van der Pol model, with axes labeled x and y .
- MathModelica System Designer:** A screenshot of the MathModelica System Designer interface showing a hierarchical tree of components and a 3D model of a mechanical system.
- Other Windows:** Several other windows showing plots, parameter settings, and simulation results, including one titled "After" showing a plot of a signal over time.

OpenModelica and Papyrus Based Model-Based Development Environment to Cover Product-Design V



Business Process Control and Modeling



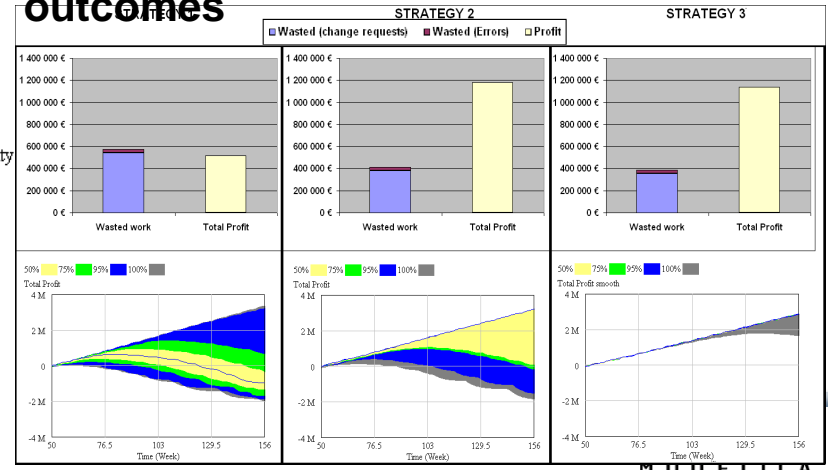
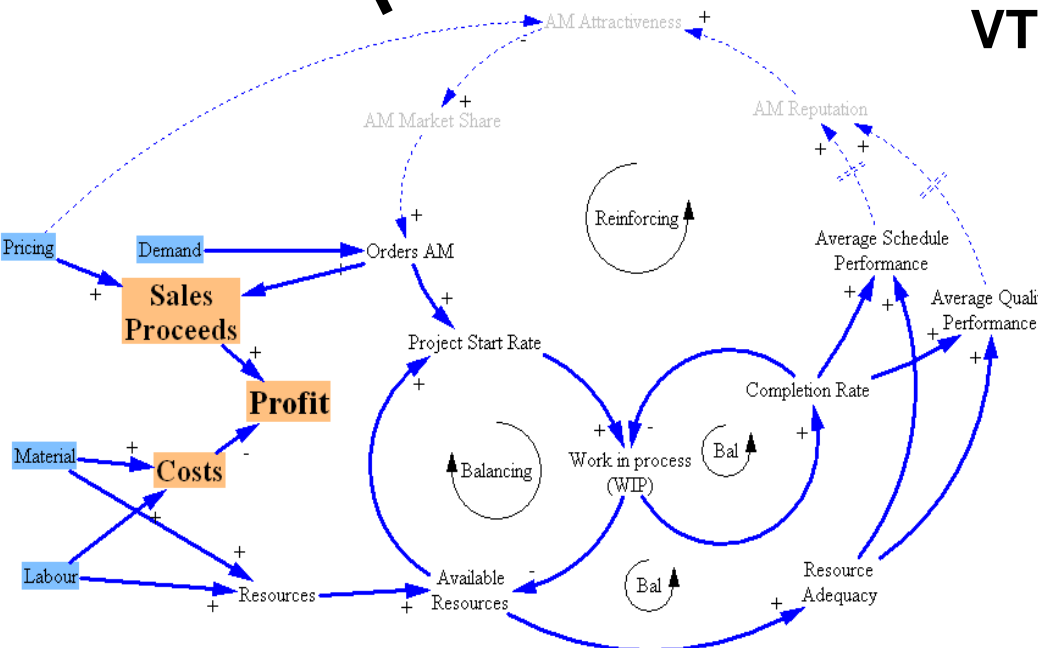
OpenModelica based simulation

VTT Simantics
Business process modeler

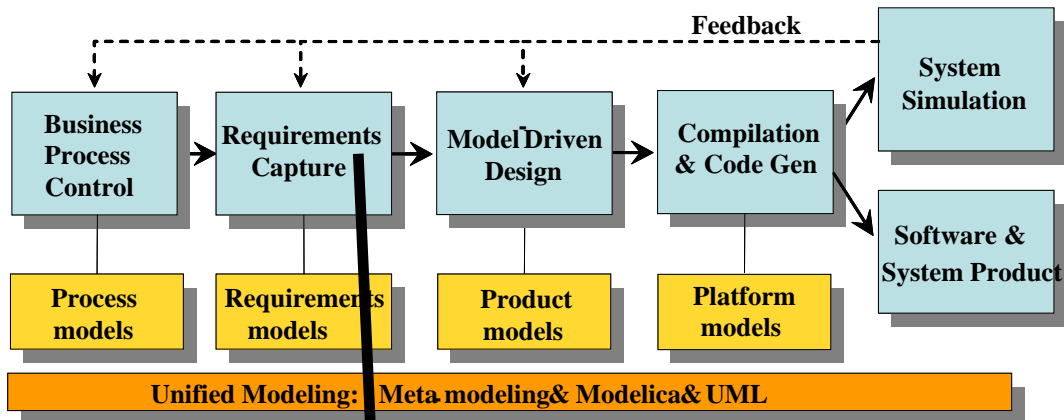
OpenModelica
compiler & simulator

Metso Business model & simulation
VTT Simantics Graphic Modeling Tool

Simulation of 3 strategies with outcomes



Requirement Capture



vVDR (virtual Verification of Designs against Requirements)

in ModelicaML UML/Modelica Profile, part of OpenModelica

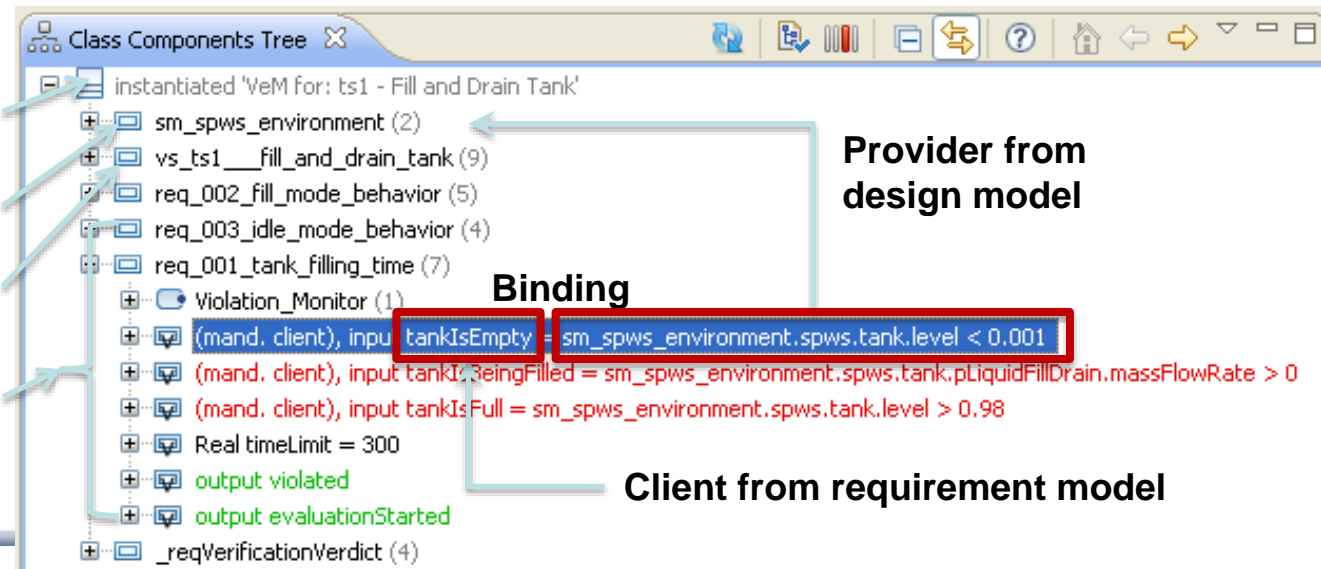
OpenModelica based simulation

Verification Model

Design Model

Scenario Model

Requirement Models

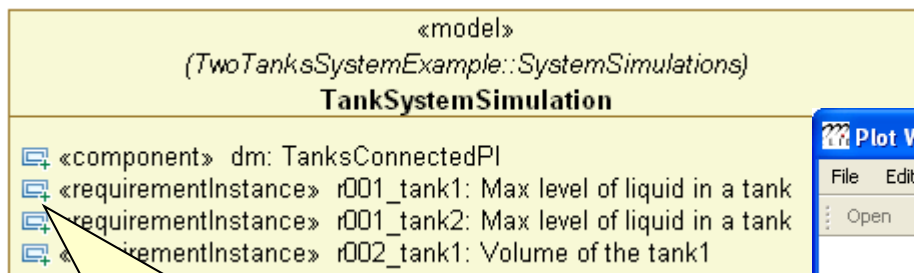


Binding

Provider from design model

Client from requirement model

Example: Simulation and Requirements Evaluation (using the ModelicaML UML/Modelica prototype)

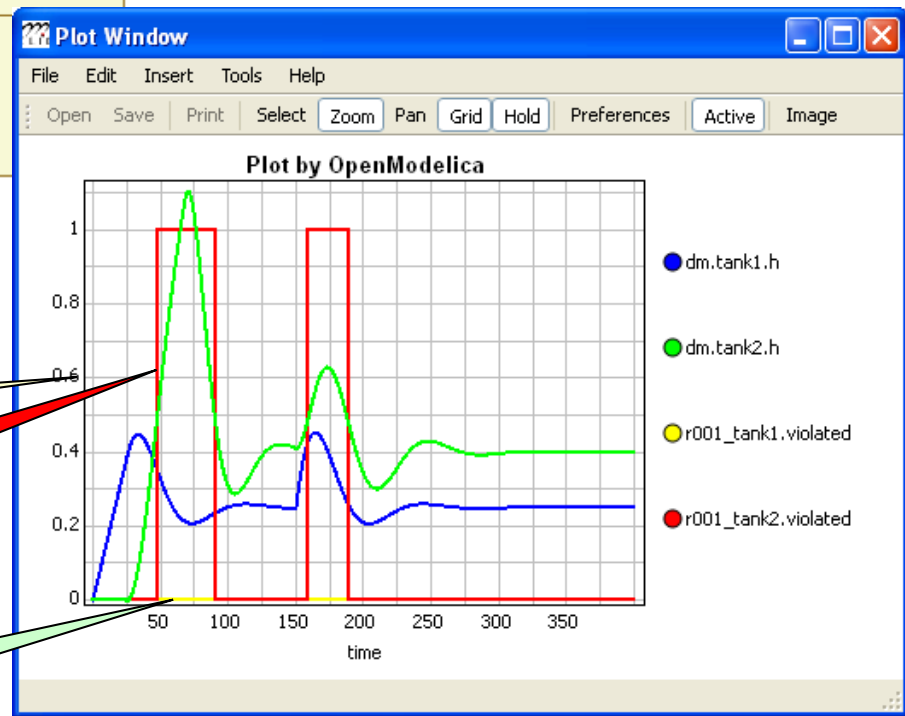


Req. 001 is instantiated 2 times (there are 2 tanks in the system)

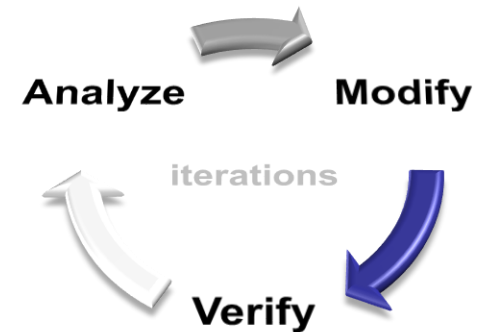
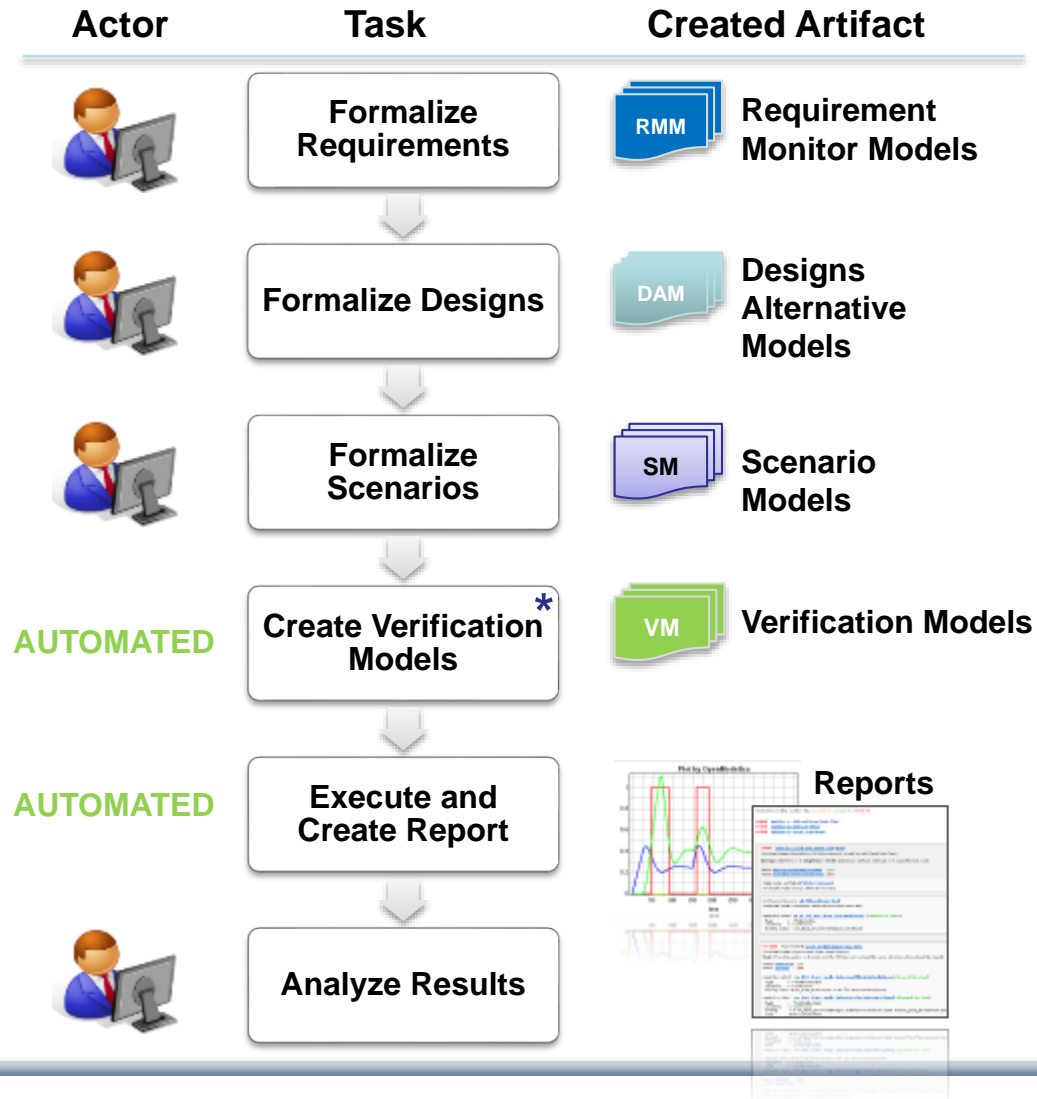
tank-height is 0.6m

Req. 001 for the tank2 is violated

Req. 001 for the tank1 is not violated



vVDR Method – virtual Verification of Designs vs Requirements

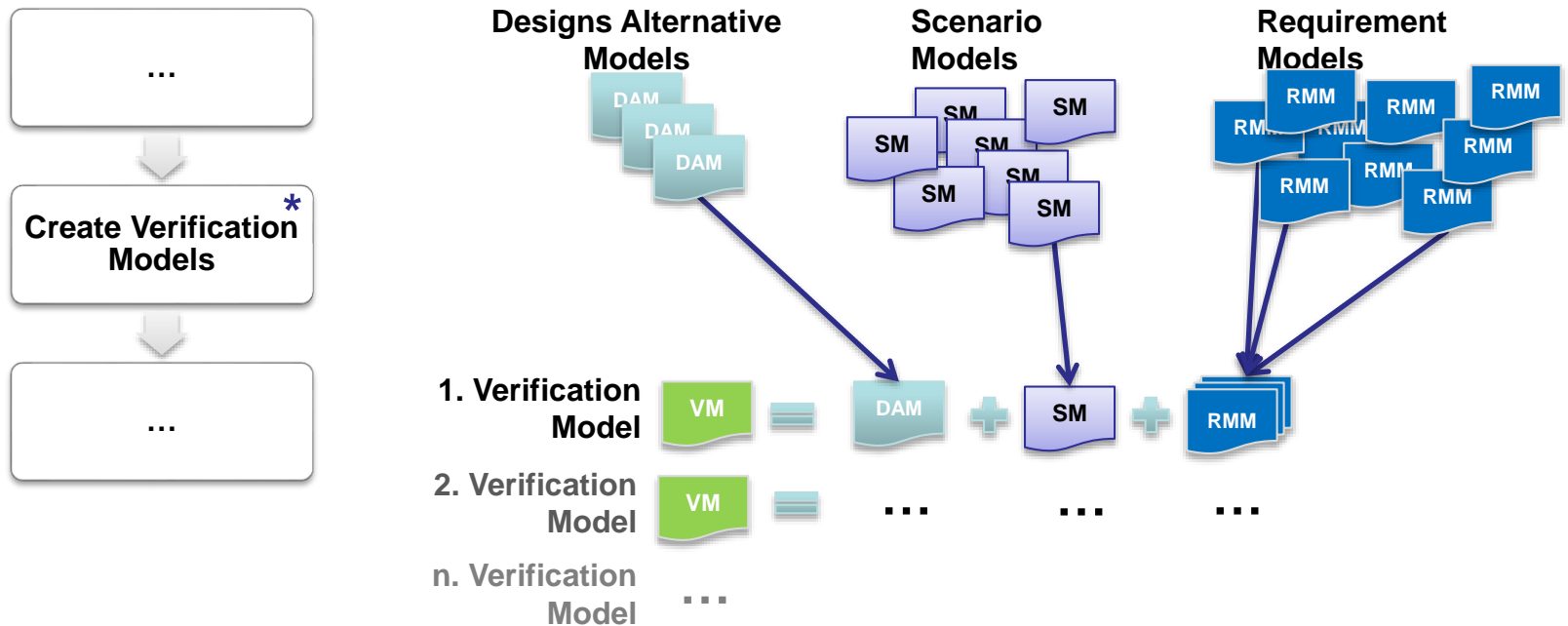


Goal: Enable on-demand verification of designs against requirements using automated model composition at any time during development.

Challenge

We want to verify **different design alternatives** against **sets of requirements** using **different scenarios**. Questions:

- 1) How to **find valid combinations** of **design alternatives**, **scenarios** and **requirements** in order to enable an automated composition of verification models?
- 2) Having found a valid combination: How to **bind all components correctly**?



Composing Verification Models

main idea

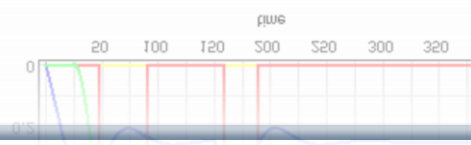
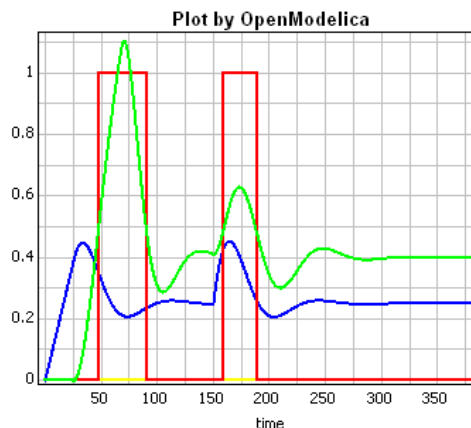
- Collect all **scenarios**, **requirements**, import **mediators**
- Generate/compose *verification models* automatically:
 - Select the **system model** to be verified
 - Find all **scenarios** that can stimulate the selected system model (i.e., for each mandatory client check whether the binding expression can be inferred)
 - Find **requirements** that are implemented in the selected system model (i.e., **check** whether for **each requirement** for all mandatory clients binding expressions can be inferred)
- Present the list of scenarios and requirements to the user
 - The user can select only a subset of scenarios or requirements he/she wishes to consider

Verification Report Generation, from Simulation of Verification Models (fr Requirements, Designs, appl scenarios)

Verification models are simulated.

The generated **Verification Report** is a prepared summary of:

- Configuration, bindings
- Violations of requirements
- etc.



Verification models number (3), executed (3), passed (0), failed (3)

Failed [VeM for: s1-Fill and Drain Tank \(Plot\)](#)

Failed [VeM for: s2-Fill tank \(Plot\)](#)

Failed [VeM for: s3-Drain tank \(Plot\)](#)

Failed [VeM for: s1-Fill and Drain Tank \(Plot\)](#)

(ModelicaMLModel::GenVeMs for: SPWS Environment_1::VeM for: s1-Fill and Drain Tank)

Settings: startTime = 0, stopTime = 1500, tolerance = default, intervals = 0, outputFormat = plt

verdict [allRequirementsEvaluated](#) : yes

verdict [someRequirementsViolated](#) : yes

Model to be verified: [SPWS Environment](#)

(ModelicaMLModel::Design::SPWS Environment)

Verification Scenario: [s1-Fill and Drain Tank](#)

(ModelicaMLModel::Verification Scenarios::s1-Fill and Drain Tank)

mandatory client: [vs s1 fill and drain tank.tankHeight](#) (changed its value)

Type : = ModelicaReal

Variability : = continuous

Binding code : = sm_spws_environment.spws.tank.height

Violated Requirement: [Drain mode behavior \(ID 004\)](#)

(ModelicaMLModel::Requirements::Drain mode behavior)

Text: When the system is drained only the fill/drain valve should be open, all other valves should be closed.

verdict [evaluated](#) : yes

verdict [violated](#) : yes

mandatory client: [req 004 drain mode behavior.fillDrainValveIsOpen](#) (changed its value)

Type : = ModelicaBoolean

Variability : = continuous

Binding code : = sm_spws_environment.spws.fillDrainValve.isFullyOpen

mandatory client: [req 004 drain mode behavior.otherValvesAreClosed](#) (changed its value)

Type : = ModelicaBoolean

Variability : = continuous

Binding code : = if sm_spws_environment.spws.overflowValve.isFullyClosed and sm_spws_environment.spws.supplyVavle.isFullyClosed
code then true else false

Support of vVDR in Modelica within OMEdit in OpenModelica

Libraries

- Mediators
 - operatingPumps
 - cavitating
 - breakMediator
- ToyExample
 - PA
 - PB
 - PumpR
 - SystemModel
 - Scenario1
 - VerifScenario1
 - Scenario2
 - SystemModelBetter
- VVDRDefinitions
 - Scenario
 - Requirement
 - Design
- BindingDefinition
 - Client
 - Provider
 - Mediator
 - Preferred

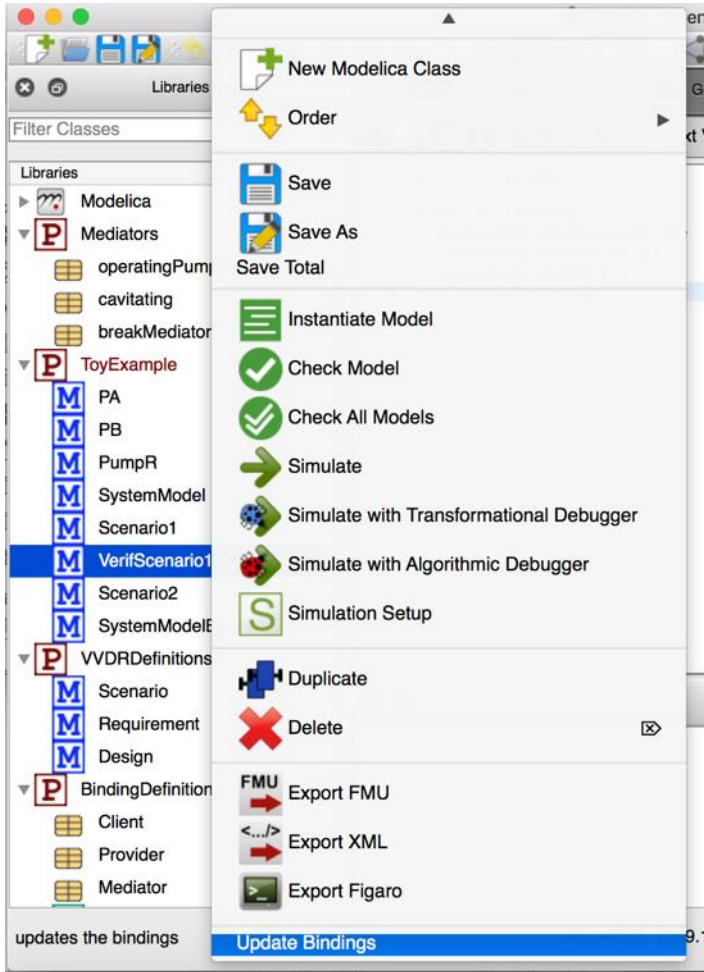
```
5 record operatingPumps
6   extends Mediator(mType = "Boolean",
7   clients = {Client(modelID = "ToyExample.PumpR", component = "inOperation")},
8   providers = {Provider(modelID = "ToyExample.PA", template = "if %getPath.on then 1 else 0"),
9     Provider(modelID = "ToyExample.PB", template = "if (%getPath.volFlowRate) > 0 then 1 else 0")}
10  );
11 end operatingPumps;
12
```

```
1 within ToyExample;
2
3 model VerifScenario1
4   ToyExample.SystemModel md;
5   ToyExample.Scenario1 s1;
6   ToyExample.PumpR r1;
7 end VerifScenario1;
```

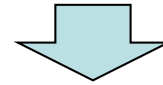
vVDR concepts in **standard Modelica**

- **mediators** mapped to **records**
- **requirements, design, scenarios** mapped to Modelica classes

Single Scenario Generation



```
1 within ToyExample;  
2  
3 model VerifScenario1  
4   ToyExample.SystemModel md;  
5   ToyExample.Scenario1 s1;  
6   ToyExample.PumpR r1;  
7 end VerifScenario1;
```



```
1 within ToyExample;  
2  
3 model VerifScenario1  
4   ToyExample.SystemModel md_autogen_bind_0(timeBreak = s1.timeFailure);  
5   ToyExample.Scenario1 s1;  
6   ToyExample.PumpR r1_autogen_bind_0(cavitate = md_autogen_bind_0.pa.cavitating);  
7   ToyExample.PumpR r1_autogen_bind_1(cavitate = md_autogen_bind_0.pb.cavitating);  
8 end VerifScenario1;
```

Generating correct number of requirement instances

Connecting the design model and the requirement

Batch Scenario Generation

The screenshot displays the Modelica IDE interface. On the left, a context menu is open, showing various actions. The 'Generate Verification Scenarios' option is highlighted at the bottom of the menu. In the center, a tree view shows the 'GenerateTests' package containing three verification models: 'verif...ogen_1', 'verif...ogen_2', and 'verif...ogen_3'. A red box highlights these three models, with an arrow pointing to the code below. The code in the bottom pane shows the implementation of these verification models within the 'GenerateTests' package.

```
1 package GenerateTests
2 model verif_model_autogen_1 "Autogenerated verification model"
3   ToyExample.PumpR _agen_PumpR2_autogen_bind_0(cavitate = _agen_SystemModelBetter0.pa.cavitating);
4   ToyExample.PumpR _agen_PumpR2_autogen_bind_1(cavitate = _agen_SystemModelBetter0.pb.cavitating);
5   ToyExample.Scenario1 _agen_Scenario11;
6   ToyExample.SystemModelBetter _agen_SystemModelBetter0_autogen_bind_0(timeBreak = _agen_Scenario11.timeFailure);
7 end verif_model_autogen_1;
8 model verif_model_autogen_2 "Autogenerated verification model"
9   ToyExample.PumpR _agen_PumpR2_autogen_bind_0(cavitate = _agen_SystemModel0.pa.cavitating);
10  ToyExample.PumpR _agen_PumpR2_autogen_bind_1(cavitate = _agen_SystemModel0.pb.cavitating);
11  ToyExample.Scenario2 _agen_Scenario21;
12  ToyExample.SystemModel _agen_SystemModel0_autogen_bind_0(timeBreak = _agen_Scenario21.timeFailure);
13 end verif_model_autogen_2;
14 model verif_model_autogen_3 "Autogenerated verification model"
15   ToyExample.PumpR _agen_PumpR2_autogen_bind_0(cavitate = _agen_SystemModel0.pa.cavitating);
16   ToyExample.PumpR _agen_PumpR2_autogen_bind_1(cavitate = _agen_SystemModel0.pb.cavitating);
17   ToyExample.Scenario1 _agen_Scenario11;
18   ToyExample.SystemModel _agen_SystemModel0_autogen_bind_0(timeBreak = _agen_Scenario11.timeFailure);
19 end verif_model_autogen_3;
20 end GenerateTests;
```


EDF SRI Case Study of vVDR Method

Conclusion and Lessons Learnt

- Showed **applicability of vVDR method** to **realistic industrial applications**
- ModelicaML is a **promising prototype** implementation of the vVDR method, needs improved usability and stability
- Lessons learnt:
 - **Formalized requirements** should be **tested separately** in order to ensure correctness
 - **Model validity asserts** must be included
 - Parameterized **requirement monitors** can be re-used as **library components** (later realized in MODRIO project)
- Later work, now ongoing
 - **Stochastic aspects** (model uncertainties, tolerances in requirements, ...) should be taken into account

What is Missing in our Systems Engineering Tool Support?

- We already have many parts of the desired environment:
 - Business process modeling
 - Requirement modeling (related to design properties)
 - Design modeling
 - Model simulation and product generation
 - Verification based on simulations
- Perhaps missing: expressing and verification of general requirements in an early phase, independent of design choices

What vs How and a Possible Requirement Language

- Desirable for **requirements** to be **independent of** particular **design** architectures
- A Design model expresses **How** to solve a problem
- A Requirement should express **What** conditions should be satisfied
- Desirable for requirements to be able to express **quantifiers, temporal constraints**, related to (sets of) objects that satisfy certain conditions
- A natural/neutral rule language for requirements? Close to **natural language?** or **borrow** many elements from an **existing modeling language**, e.g. Modelica?

Conclusions

- First step of a requirements language – **bridge/unification of UML/SysML and Modelica (ModelicaML)**, for design verification versus requirements on application scenarios
- Second step, requirements library in **Modelica** and **OpenModelica prototype** for design verification versus requirements on application scenarios
- Third step (to be realized), a formal **requirement language** to express basic requirement **rules**, for **early requirement debugging and verification** without the need for a (detailed) system architecture