

# Lecture 2b

---

## Equations

# Usage of Equations

In Modelica equations are used for many tasks

- The main usage of equations is to represent relations in mathematical models.
- *Assignment statements* in conventional languages are usually represented as equations in Modelica
- *Attribute assignments* are represented as equations
- Connections between objects generate equations

# Equation Categories

Equations in Modelica can informally be classified into three different categories

- *Normal equations* (e.g.,  $expr1 = expr2$ ) occurring in equation sections, including `connect` equations and other equation types of special syntactic form
- *Declaration equations*, (e.g., `Real x = 2.0`) which are part of variable, parameter, or constant declarations
- *Modifier equations*, (e.g. `x(unit="V")`) which are commonly used to modify attributes of classes.

# Constraining Rules for Equations

## Single Assignment Rule

The total number of “equations” is identical to the total number of “unknown” variables to be solved for

## Synchronous Data Flow Principle

- All variables keep their actual values until these values are explicitly changed
- At every point in time, during “continuous integration” and at event instants, the *active* equations express relations between variables which have to be fulfilled *concurrently*  
Equations are not active if the corresponding `if`-branch or `when`-equation in which the equation is present is not active because the corresponding branch condition currently evaluates to `false`
- Computation and communication at an event instant does not take time

# Declaration Equations

Declaration equations:

```
constant Integer one = 1;  
parameter Real mass = 22.5;
```

It is also possible to specify a declaration equation for a normal non-constant variable:

```
Real speed = 72.4;
```

declaration  
equations ←

```
model MoonLanding  
  parameter Real force1 = 36350;  
  parameter Real force2 = 1308;  
  parameter Real thrustEndTime = 210;  
  parameter Real thrustDecreaseTime = 43.2;  
  Rocket      apollo(name="apollo13", mass(start=1038.358) );  
  CelestialBody moon(mass=7.382e22, radius=1.738e6, name="moon");  
  equation  
    apollo.thrust = if (time<thrustDecreaseTime) then force1  
                    else if (time<thrustEndTime) then force2  
                    else 0;  
    apollo.gravity=moon.g*moon.mass/(apollo.altitude+moon.radius)^2;  
end Landing;
```

# Modifier Equations

Modifier equations occur for example in a variable declaration when there is a need to modify the default value of an attribute of the variable  
A common usage is modifier equations for the start attribute of variables

```
Real speed(start=72.4);
```

Modifier equations also occur in type definitions:

```
type Voltage = Real(unit="V", min=-220.0, max=220.0);
```

```
model MoonLanding
  parameter Real force1 = 36350;
  parameter Real force2 = 1308;
  parameter Real thrustEndTime = 210;
  parameter Real thrustDecreaseTime = 43.2;
  Rocket      apollo(name="apollo13", mass(start=1038.358) );
  CelestialBody moon(mass=7.382e22, radius=1.738e6, name="moon");
equation
  apollo.thrust = if (time<thrustDecreaseTime) then force1
                  else if (time<thrustEndTime) then force2
                  else 0;
  apollo.gravity=moon.g*moon.mass/(apollo.altitude+moon.radius)^2;
end Landing;
```

modifier  
equations ←

# Kinds of Normal Equations in Equation Sections

Kinds of equations that can be present in equation sections:

- equality equations
- connect equations
- assert and terminate
- reinit
- repetitive equation structures with `for`-equations
- conditional equations with `if`-equations
- conditional equations with `when`-equations

```
model MoonLanding
  parameter Real force1 = 36350;
  parameter Real force2 = 1308;
  parameter Real thrustEndTime = 210;
  parameter Real thrustDecreaseTime = 43.2;
  Rocket      apollo(name="apollo13", mass(start=1038.358) );
  CelestialBody moon(mass=7.382e22,radius=1.738e6,name="moon");

  equation
    if (time<thrustDecreaseTime) then
      apollo.thrust = force1;
    elseif (time<thrustEndTime) then
      apollo.thrust = force2;
    else
      apollo.thrust = 0;
    end if;
    apollo.gravity=moon.g*moon.mass/(apollo.altitude+moon.radius)^2;
end Landing;
```

conditional  
if-equation

equality  
equation

# Equality Equations

```
expr1 = expr2:  
(out1, out2, out3, ...) = function_name(in_expr1, in_expr2, ...);
```

simple equality  
equation ←

```
class EqualityEquations  
  Real x, y, z;  
equation  
  (x, y, z) = f(1.0, 2.0); // Correct!  
  (x+1, 3.0, z/y) = f(1.0, 2.0); // Illegal!  
                                     // Not a list of variables  
                                     // on the left-hand side  
end EqualityEquations;
```

# Repetitive Equations

The syntactic form of a `for`-equation is as follows:

```
for <iteration-variable> in <iteration-set-expression> loop
  <equation1>
  <equation2>
  ...
end for;
```

Consider the following simple example with a `for`-equation:

```
class FiveEquations
  Real[5] x;
equation
  for i in 1:5 loop
    x[i] = i+1;
  end for;
end FiveEquations;
```

**Both classes have  
equivalent behavior!**



```
class FiveEquationsUnrolled
  Real[5] x;
equation
  x[1] = 2;
  x[2] = 3;
  x[3] = 4;
  x[4] = 5;
  x[5] = 6;
end FiveEquationsUnrolled;
```

In the class on the right the `for`-equation has been unrolled into five simple equations

# connect-equations

In Modelica `connect`-equations are used to establish connections between components via connectors

```
connect(connector1,connector2)
```

## Repetitive `connect`-equations

```
class RegComponent
  Component components[n];
equation
  for i in 1:n-1 loop
    connect(components[i].outlet,components[i+1].inlet);
  end for;
end RegComponent;
```

# Conditional Equations: *if*-equations

```
if <condition> then
  <equations>
elseif <condition> then
  <equations>
else
  <equations>
end if;
```

*if*-equations for which the conditions have higher variability than constant or parameter must include an *else-part*

Each *then*-, *elseif*-, and *else*-branch must have the *same number of equations*

```
model MoonLanding
  parameter Real force1 = 36350;
  ...
  Rocket      apollo(name="apollo13", mass(start=1038.358) );
  CelestialBody moon(mass=7.382e22,radius=1.738e6,name="moon");
equation
  if (time<thrustDecreaseTime) then
    apollo.thrust = force1;
  elseif (time<thrustEndTime) then
    apollo.thrust = force2;
  else
    apollo.thrust = 0;
  end if;
  apollo.gravity=moon.g*moon.mass/(apollo.altitude+moon.radius)^2;
end Landing;
```

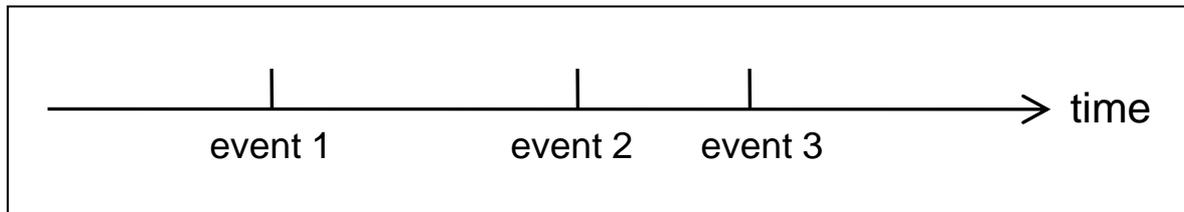
# Conditional Equations: when-equations

```
when <conditions> then  
  <equations>  
end when;
```

```
when x > 2 then  
  y1 = sin(x);  
  y3 = 2*x + y1+y2;  
end when;
```

<equations> in when-equations are instantaneous equations that are active at events when <conditions> become true

Events are ordered in time and form an event history:



- An event is a *point* in time that is instantaneous, i.e., has zero duration
- An *event condition* switches from false to true in order for the event to take place

# Conditional Equations: when-equations cont'

```
when <conditions> then
  <equations>
end when;
```

*when-equations* are used to express instantaneous equations that are only valid (become active) *at events*, e.g. at discontinuities or when certain conditions become true

```
when x > 2 then
  y1 = sin(x);
  y3 = 2*x + y1+y2;
end when;
```

```
when {x > 2, sample(0,2), x < 5} then
  y1 = sin(x);
  y3 = 2*x + y1+y2;
end when;
```

```
when initial() then
  ... // Equations to be activated at the beginning of a simulation
end when;
...
when terminal() then
  ... // Equations to be activated at the end of a simulation
end when;
```

# Restrictions on when-equations

## Form restriction

```
model WhenNotValid
  Real x, y;
  equation
    x + y = 5;
  when sample(0,2) then
    2*x + y = 7;
    // Error: not valid Modelica
  end when;
end WhenNotValid;
```

Modelica restricts the allowed equations within a when-equation to: **variable = expression**, if-equations, for-equations,...

In the `WhenNotValid` model when the equations within the when-equation are not active it is not clear which variable, either `x` or `y`, that is a “result” from the when-equation to keep constant outside the when-equation.

A corrected version appears in the class `WhenValidResult` below

```
model WhenValidResult
  Real x, y;
  equation
    x + y = 5;           // Equation to be used to compute x.
  when sample(0,2) then
    y = 7 - 2*x;        // Correct, y is a result variable from the when!
  end when;
end WhenValidResult;
```

# Restrictions on when-equations cont'

## Restriction on nested when-equations

```
model ErrorNestedWhen
  Real x,y1,y2;
  equation
    when x > 2 then
      when y1 > 3 then // Error!
        y2 = sin(x); // when-equations
      end when; // should not be nested
    end when;
end ErrorNestedWhen;
```

when-equations cannot be nested!

# Restrictions on when-equations cont'

Single assignment rule: same variable may not be defined in several `when`-equations.

A conflict between the equations will occur if both conditions would become true at the same time instant

```
model DoubleWhenConflict
  Boolean close; // Error: close defined by two equations!
equation
  ...
  when condition1 then
    close = true; // First equation
  end when;
  ...
  when condition2 then
    close = false; //Second equation
  end when;
end DoubleWhenConflict
```

# Restrictions on when-equations cont'

Solution to assignment conflict between equations in independent when-equations:

- Use `elsewhen` to give higher priority to the first when-equation

```
model DoubleWhenConflictResolved
  Boolean close;
equation
  ...
  when condition1 then
    close = true; // First equation has higher priority!
  elsewhen condition2 then
    close = false; //Second equation
  end when;
end DoubleWhenConflictResolved
```

# Restrictions on when-equations cont'

## Vector expressions

The equations within a `when`-equation are activated when any of the elements of the vector expression becomes true

```
model VectorWhen
  Boolean close;
equation
  ...
  when {condition1,condition2} then
    close = true;
  end when;
end DoubleWhenConflict
```

# assert-equations

```
assert(assert-expression, message-string)
```

`assert` is a predefined function for giving error messages taking a Boolean condition and a string as an argument

The intention behind `assert` is to provide a convenient means for specifying checks on model validity within a model

```
class AssertTest
  parameter Real lowlimit = -5;
  parameter Real highlimit = 5;
  Real x;
equation
  assert(x >= lowlimit and x <= highlimit,
         "Variable x out of limit");
end AssertTest;
```

# terminate-equations

The `terminate-equation` successfully terminates the current simulation, i.e. no error condition is indicated

```
model MoonLanding
  parameter Real force1 = 36350;
  parameter Real force2 = 1308;
  parameter Real thrustEndTime = 210;
  parameter Real thrustDecreaseTime = 43.2;
  Rocket      apollo(name="apollo13", mass(start=1038.358) );
  CelestialBody moon(mass=7.382e22,radius=1.738e6,name="moon");
equation
  apollo.thrust = if (time<thrustDecreaseTime) then force1
                  else if (time<thrustEndTime) then force2
                  else 0;
  apollo.gravity = moon.g * moon.mass / (apollo.height + moon.radius)^2;
  when apollo.height < 0 then // termination condition
    terminate("The moon lander touches the ground of the moon");
  end when;
end MoonLanding;
```